

### Reducing time errors from GNSS -Time for multi-Band?

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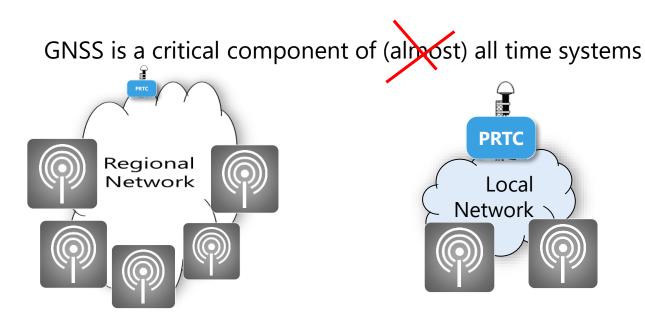
#### **Motivation & Background**

(for <u>high accuracy time</u> )

- 1. GNSS easier timing deployment
- 5G, small-cell ... Power; Financial;...
- 2. GNSS higher timing accuracy
- Integrated-GM Measurement results
- 3. GNSS improved timing resiliency
- Backup and monitoring are essential



#### With the same challenges



**GNSS** everywhere...

**Remote Dependence** 

Local Dependence

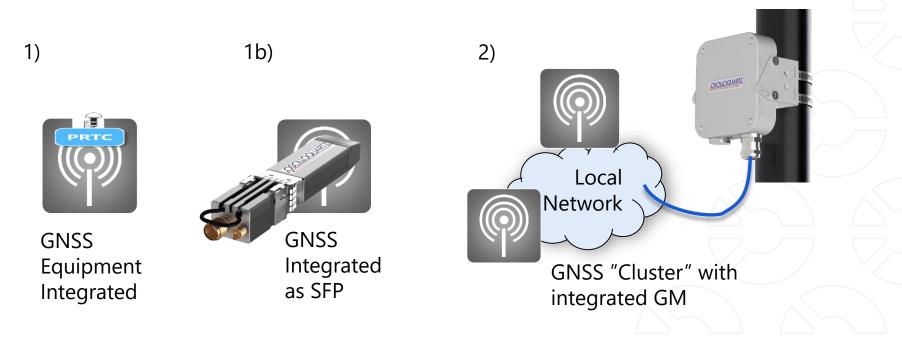
PRIC

Embedded Dependence



### **GNSS - enabler for fast Time rollout**

Options:

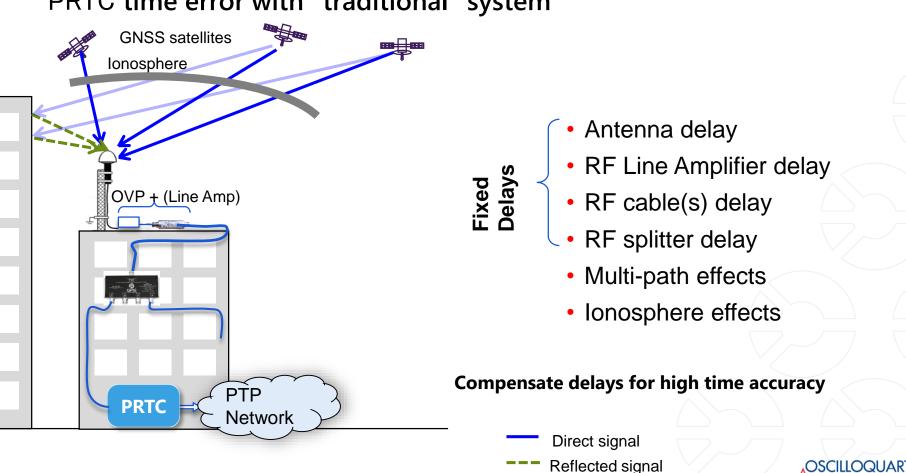




## Sources of GNSS time errors

|  |           | Magnitude |        | Mitigation           |
|--|-----------|-----------|--------|----------------------|
| 1) Antenna/cable delay (error)           |           | ?         |        | Measure or Integrate |
| 2) Multipath effects (deep urban canyon) |           | 10-100ns  |        | Design               |
| 3) Ionosphere variations                 |           | 20 -      | - 50ns | Multiband            |
| 4) Local interference (jamming)          | Multiband | ?         |        | Monitoring & Backup  |
| 5) Deliberate attack (spoofing)          | Helps     | ?         |        | Monitoring & Backup  |
| 6) GNSS antenna / receiver failure       |           | ?         |        | Monitoring & Backup  |





#### PRTC time error with "traditional" system

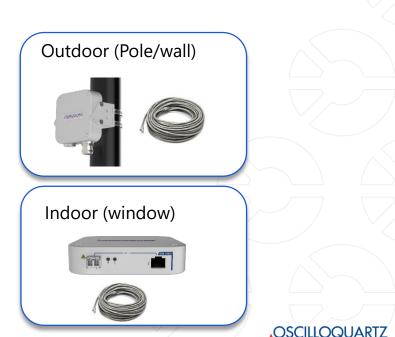
#### 1) Removing Antenna/cable delays



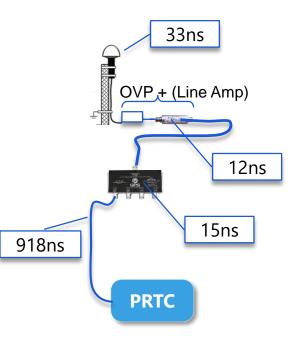
#### Integrated GrandMaster - with extras (APTS, monitoring...)

- Fast, Easy Installation
- Optimized for partial sky view
- Ethernet cabling Copper or Fibre
- (No RF-cabling required)





## **RF delays – site specific compensation**

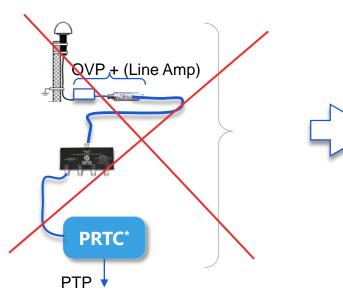


| Antenna Vendor | Typical delay | Delay variation |
|----------------|---------------|-----------------|
| A (commercial) | 23nsec        | +/-15           |
| B (commercial) | 19nsec        | +/-10           |
| C (high end)   | 10nsec        | +/-5            |

#### Accurate compensation of RF delays is difficult!



#### Move to Integrated GrandMaster (and avoid the RF delay problem)







Indoors





#### \* PRTC includes GM function

# 2) Design for minimal multipath

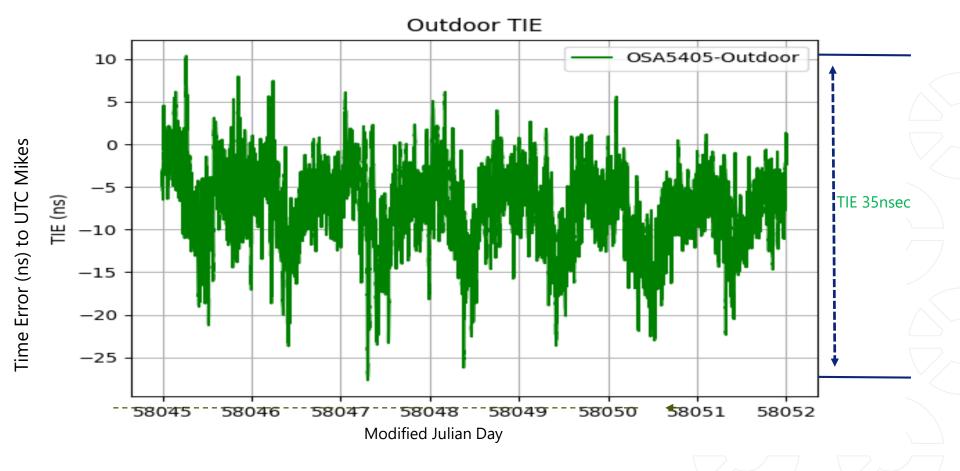


#### Testing at national lab (VTT MIKEs) #1 Indoor (glass bricks); #2 Outdoor (wall)



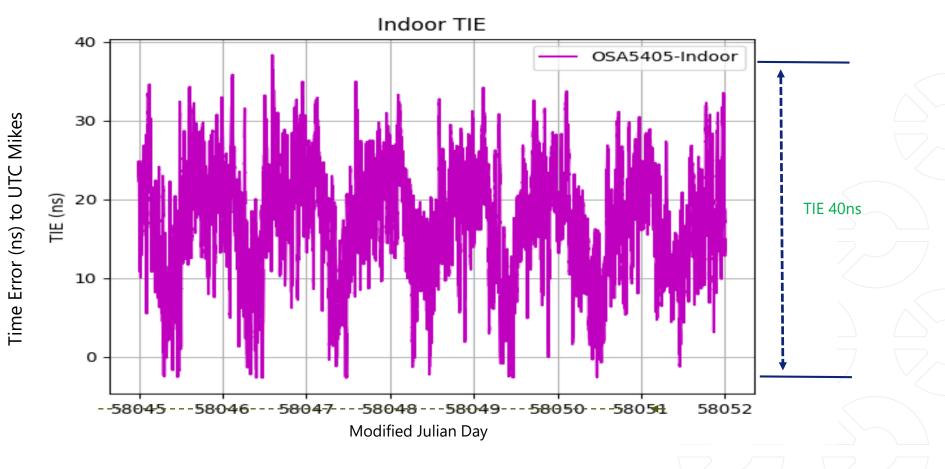


#### Test results (~1 week) 5405 Outdoor



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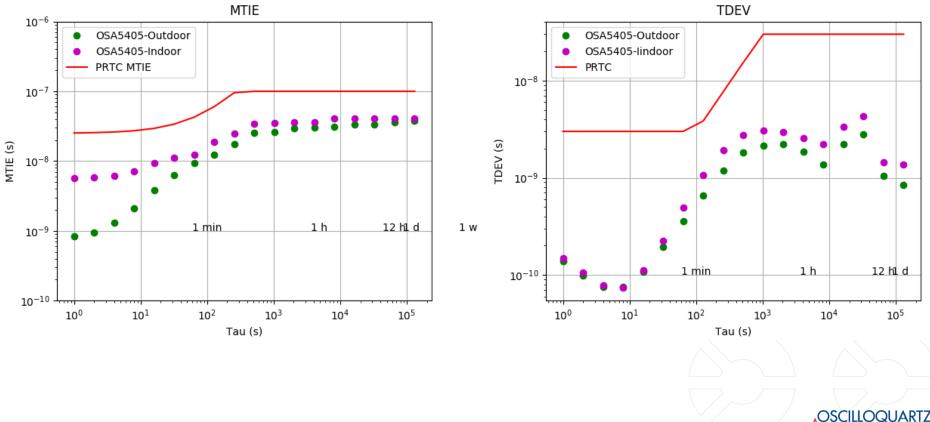
#### VTT Test results (~1 week) 5405 Indoor





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#### **VTT Test results – MTIE / TDEV**

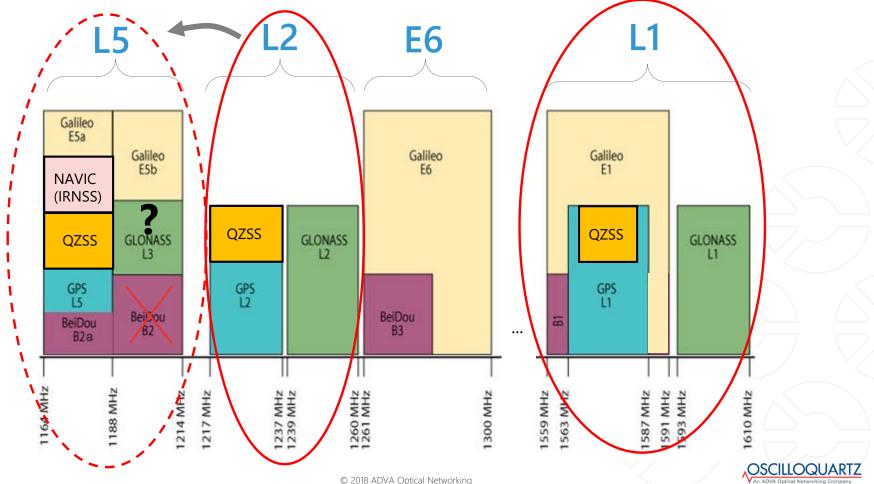


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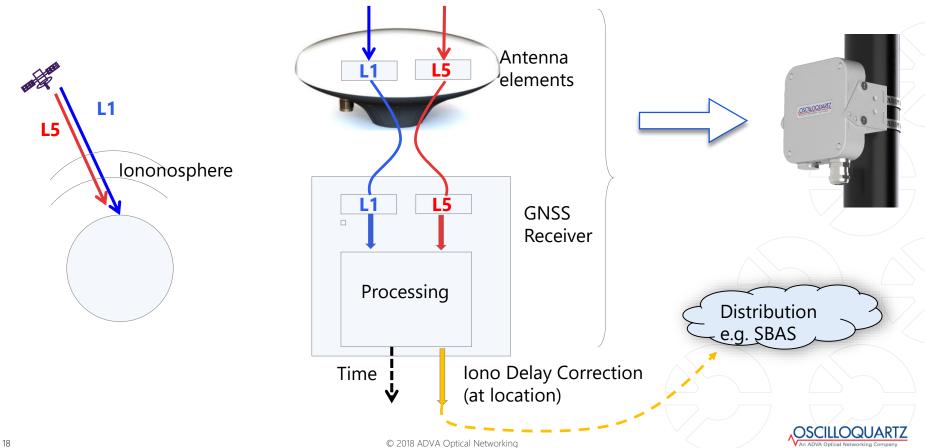
#### 3) Ionosphere delay - the case for multiband



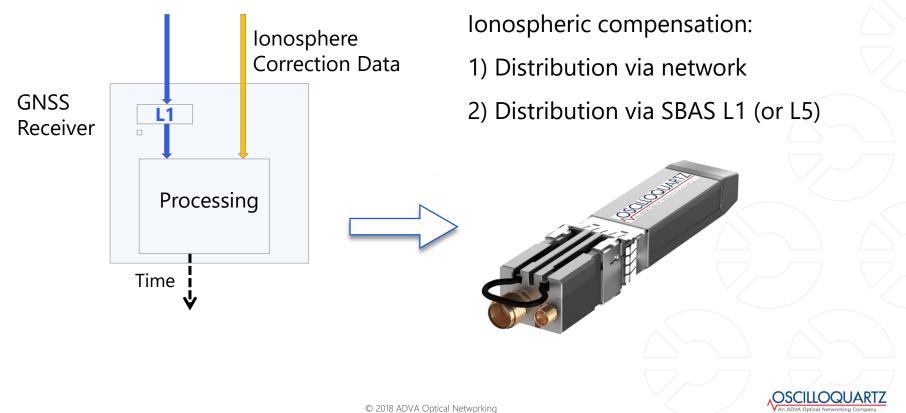
GNSS Multiband = L1 + ?



## **Ionospheric delay correction**



#### **Benefits of multi-band for L1 receivers**



19

### **Benefits of networking GNSS devices**

Service management (Back-up and optimization)

Network management (monitors each clock)



#### Network >> sum of parts



#### 4) Synchronization service -Monitoring and backup



#### **Essentials for robust time provisioning**

2. Monitor and correlate Key Performance Indicators (KPIs)

| GM Monitoring  | KPIs  | a fiction   |  |
|----------------|---|---|--|
| GNSS data      | #Carrier locked Satelites<br>SNRs; AGC<br>Jamming, Spoofing, warnings | B Multis Cock Accuracy Cock Accurac   | CLOCE ACQUIACY<br>CLOCE ACQUIACY<br>Clock Prote Status<br>Clock Prote Status |
| GNSS V PTP     | MTIE (after assymetry correction)                                     | In     Autom     IN     Autom     Autom       1     0.04 </td <td>ur unfilien</td>   | ur unfilien  |
| GNSS V SyncE   | MTIE  | i Gravnikani<br>i Gravinski<br>vrazivnika<br>i Baladon<br>kolesialar<br>i Saladon<br>i Saladon |  |
| GNSS V OCXO    | Freq offset (ppb)   | +   |  |
| Network of clo |   |   |  |
|                | © 2018 ADVA Optical Networking  |   |  |

#### **Correlate GNSS KPIs**

| DI Monitoring (Location P)  | Pessible Events               |
|-----------------------------|-------------------------------|
| KPI Monitoring (Location C) | Possible Events               |
| GNSS V OCXO                 | Rapid adjustment              |
| GNSS V Remote clock         | MTIE outage                   |
| GNSS data                   | Suspected: Spoofing; Jamming; |



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### Conclusions

- 1) Compensation of unknown delays is key to accuracy
  - "Cable" delays avoid with Ethernet cabling
  - Ionospheric delays use multiband receiver or
  - (L1 receivers compensate via SBAS or Network)

- 2) Use the network for making timing services
  - Monitor and correlate KPIs





selecting the right wave improves packet clock performance



Teleconi Can't you behave like an Ordinary clock?





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**Thank You** 



#### Thank you



#### IMPORTANT NOTICE

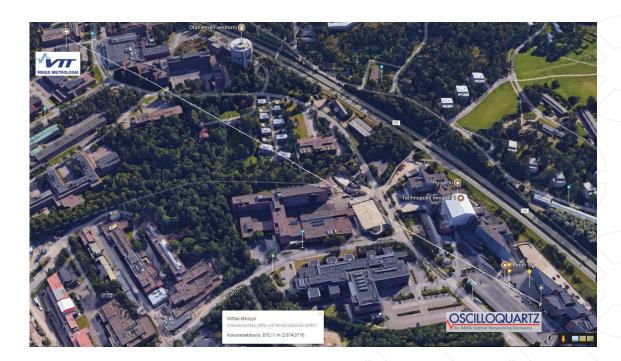
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# **Testing at VTT MIKES**

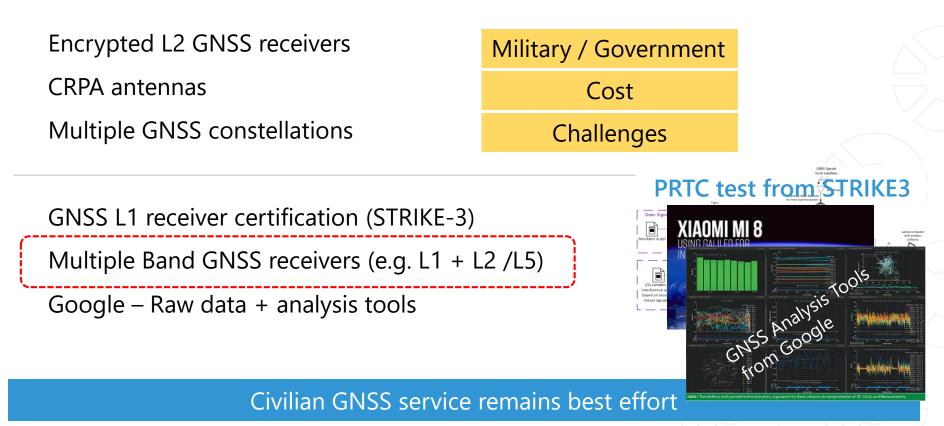
- VTT provides UTC MIKES
- Distance 876m
- Fibre connection
- PTP White Rabbit
- Accuracy UTC ~5ns



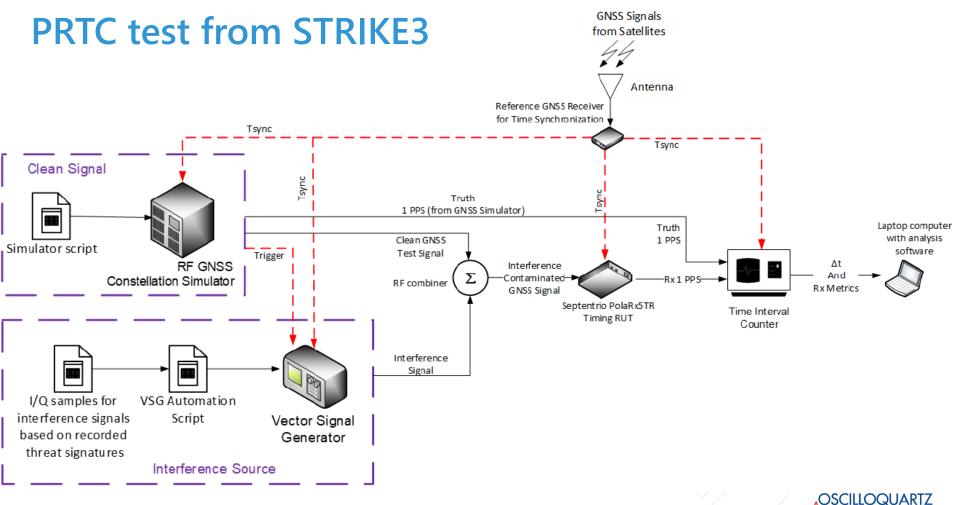
Link to Finnish Time keeper VTT MIKES



### **Improvements to GNSS technology**







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# STRIKE3 – One effort to document and categorize GNSS threats.

Standardisation of GNSS Threat reporting and Receiver testing through International Knowledge Exchange, Experimentation and Exploitation

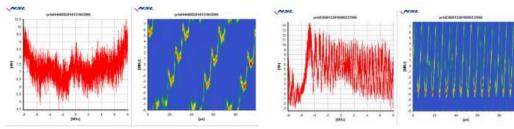
Funded by EU-H2020 programme (Galileo)

Fingerprinting jamming techniques focusing on the RF waveform

Field recording-> Lab analysis -> Test playback

D4.2 Draft standard for receiver testing against threats

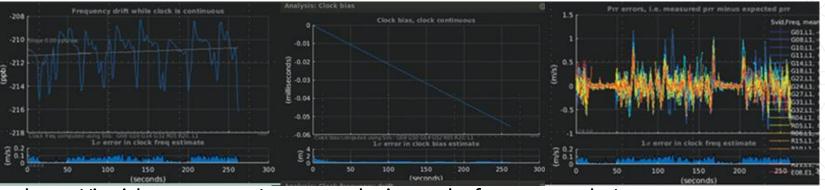
considers jamming interference only in GPS L1 / Galileo E1



http://www.gnss-strike3.eu/

#### Data available from GNSS receivers?

- 1. Google released GNSS raw data on Android. Also GNSS Analysis Tools to process and analyze raw data.
- 2. Raw measurement data shows the receiver clock to better than 1ppb precision.
- 3. Raw data allows insight into the signal environment and receiver behaviour
- 4. Chipset vendors provide API, but raw GNSS data ?



http://insidegnss.com/gnss-analysis-tools-from-google/



### Some of the Raw attributes available (Google GNSS)

| Analysis: C(No strongest sats  |  |  |  |  |
|--|--|--|--|--|
| GnssClock  |  | 1                                      | Satellite ID                                       |  |
| TimeNanos GNSS Receiver hardware clock value   |  |  | BeiDou, Galileo, GLONASS, GPS, QZSS, SBAS          |  |
| TimeUncertaintyNanos Uncertainty of above value -  |  | 1_                                     | Time offset if measurements are asynchronous       |  |
| FullBiasNanos  | Difference between receiver clock and true GPS | 1                                      | Sync state (Code lock, bit sync, frame sync, etc.) |  |
|  | time since 0000Z, January 6, 1980.             |  | Received satellite time, at the measurement time   |  |
| BiasNanos  | Sub-nanosecond part of above number            |  | Error estimate of above value                      |  |
| DriftNanosPerSecond  | Receiver clock's drift                         | 1                                      | Carrier-to-noise density ratio                     |  |
| DriftUncertaintyNanosPerSecond   | Uncertainty of above value                     | 1                                      | Pseudorange rate (-Doppler)                        |  |
| a HardwareClockDiscontinuityCount  | Count of hardware clock discontinuities        | nd                                     | Error estimate of above value                      |  |
| alysis: Skyplot O Analysis: Clock fro<br>-208 r  | requency drift<br>Frequency dri                |  | Accumulated delta range (carrier phase)            |  |
| 50     014     -708       51     412     601.11     -210       52     424     668.11     -210  | A AccumulatedDeltaRangeUncertaintyMeters       | AccumulatedDeltaRangeUncertaintyMeters |  |  |
| 20// / CG401 15 / CE20 60011   | AccumulatedDeltaRangeState                     |  | Valid, Cycle slip or Loss-of-lock/Reset            |  |
|  |  |  | Carrier frequency of the tracked signal            |  |
| 100 + 100 + 001 + 001 + 001 - 001 100 - 001 - 000  | AgcDb  |  | Automatic Gain Control level                       |  |
| $\frac{1}{1000} \frac{1}{1000} \frac{1}{1000$ |  |  |  |  |

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FIGURE 1 The desktop tools provide interactive plots, organized into three columns showing behavior of: RF, Clock, and Measurements.